

# GENERATING LANGUAGE-BASED ENVIRONMENTS

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THOMAS W. REPS

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# Generating Language Based Environments Acm Doctoral Dissertation Award

**Thomas W. Reps, Tim Teitelbaum**



## **Generating Language Based Environments Acm Doctoral Dissertation Award:**

**Generating Language-based Environments** Thomas W. Reps, 1982 This thesis concerns the design of interactive language based programming environments that use knowledge of a programming language to provide functions based on the structure and meaning of programs The goal of the research is a system constructor to enable editors for different languages to be created easily *Language Architectures And Programming Environments* F Baiardi, Tadao Ichikawa, L Lapriore, H Tsubotani, 1992-07-15 This book contains articles on advanced topics in language architectures and programming environments The chapters are written by distinctive leaders in their respective research fields The original articles and reprints are enhanced by the editors descriptions which are intended to guide the reader The book will be of immense use to computer science students computer system architects and designers and designers of programming environments requiring a deep and broad knowledge of these fields

**Generating Language-based Environments** Thomas William Reps, 1984-01 This book addresses a fundamental software engineering issue applying formal techniques and rigorous analysis to a practical problem of great current interest the incorporation of language specific knowledge in interactive programming environments It makes a basic contribution in this area by proposing an attribute grammar framework for incremental semantic analysis and establishing its algorithmic foundations The results are theoretically important while having immediate practical utility for implementing environment generating systems The book s principal technical results include an optimal time algorithm to incrementally maintain a consistent attributed tree of attribute grammar subclasses allowing an optimizing environment generator to select the most efficient applicable algorithm a general method for sharing storage among attributes whose values are complex data structures and two algorithms that carry out attribute evaluation while reducing the number of intermediate attribute values retained While others have worked on this last problem Reps s algorithms are the first to achieve sublinear worst case behavior One algorithm is optimal achieving the  $\log n$  lower space bound in nonlinear time while the second algorithm uses as much as  $\sqrt{n}$  space but runs in linear time

**The Synthesizer Generator** Thomas W. Reps, Tim Teitelbaum, 2012-12-06 This book is a detailed account of the Synthesizer Generator a system for creating specialized editors that are customized for editing particular languages The book is intended for those with an interest in software tools and in methods for building interactive systems It is a must for people who are using the Synthesizer Generator to build editors because it provides extensive discussions of how to write editor specifications The book should also be valuable for people who are building specialized editors by hand without using an editor generating tool The need to manage the development of large software systems is one of the most pressing problems faced by computer programmers An important aspect of this problem is the design of new tools to aid interactive program development The Synthesizer Generator permits one to create specialized editors that are tailored for editing a particular language In program editors built with the Synthesizer Generator knowledge about the language is used to continuously assess whether a program

contains errors and to determine where such errors occur The information is then displayed on the terminal screen to provide feed back to the programmer as the program is developed and modified

**Algorithmic Learning Theory II** Setsuo Arikawa, Akira Maruoka, T. Sato, 1992

**Systematic Program Design**, 2013

**Compiler Compilers** Dieter Hammer, 1991-02-12 Advances and problems in the field of compiler compilers are considered in this volume which presents the proceedings of the third in a series of biannual workshops on compiler compilers Selected papers address the topics of requirements properties and theoretical aspects of compiler compilers as well as tools and metatools for software engineering The 23 papers cover a wide spectrum in the field of compiler compilers ranging from overviews of new compiler compilers for generating quality compilers to special problems of code generation and optimization Aspects of compilers for parallel systems and knowledge based development tools are also discussed

**The Complexity of Robot Motion Planning** John Canny, 1988 The Complexity of Robot Motion Planning makes original contributions both to robotics and to the analysis of algorithms In this groundbreaking monograph John Canny resolves long standing problems concerning the complexity of motion planning and for the central problem of finding a collision free path for a jointed robot in the presence of obstacles obtains exponential speedups over existing algorithms by applying high powered new mathematical techniques Canny's new algorithm for this generalized movers problem the most studied and basic robot motion planning problem has a single exponential running time and is polynomial for any given robot The algorithm has an optimal running time exponent and is based on the notion of roadmaps one dimensional subsets of the robot's configuration space In deriving the single exponential bound Canny introduces and reveals the power of two tools that have not been previously used in geometrical algorithms the generalized multivariable resultant for a system of polynomials and Whitney's notion of stratified sets He has also developed a novel representation of object orientation based on unnormalized quaternions which reduces the complexity of the algorithms and enhances their practical applicability After dealing with the movers problem the book next attacks and derives several lower bounds on extensions of the problem finding the shortest path among polyhedral obstacles planning with velocity limits and compliant motion planning with uncertainty It introduces a clever technique path encoding that allows a proof of NP hardness for the first two problems and then shows that the general form of compliant motion planning a problem that is the focus of a great deal of recent work in robotics is non deterministic exponential time hard Canny proves this result using a highly original construction John Canny received his doctorate from MIT and is an assistant professor in the Computer Science Division at the University of California Berkeley The Complexity of Robot Motion Planning is the winner of the 1987 ACM Doctoral Dissertation Award

**CMU Computer Science** Richard F. Rashid, 1991

Presentations from a technical symposium held in commemoration of the 25th anniversary of the Carnegie Mellon U Computer Science Department range from thoughtful retrospectives to careful examinations of the state of the art in such areas as parallel systems programming languages artificial intel

*Research in Engineering and Applied Science at Cornell*

University, 1984      **Proceedings of the PCTE '94 Conference** Timothy Lindquist, Harry Koehnemann, 1994

**Electronic Design Automation Frameworks** Tom Rhyne, 1992 Many of the advances achieved in framework technology during the last five years are reported in this volume However despite acknowledged developments and an enormous investment by the Computer Aided Design CAD vendor industry and others commercial framework products have been slow to appear on the market Further those which have appeared have largely failed to meet original targets whether in terms of scope or performance or both Reaching a consensus on new international standards has been a painfully slow process with rapid advances in technology often rendering new standards out of date even before their eventual appearance A motivation for agreement on technical issues not yet fully understood or researched will be vital if a commercial basis to underpin future development is to be achieved It is hoped this book will stimulate interchange between researchers developers and users so that practical progress can be made backed by the strong support of interested industries

*Systematic Program Design* Yanhong Annie Liu, 2013-05-20 A systematic program design method can help developers ensure the correctness and performance of programs while minimizing the development cost This book describes a method that starts with a clear specification of a computation and derives an efficient implementation by step wise program analysis and transformations The method applies to problems specified in imperative database functional logic and object oriented programming languages with different data control and module abstractions Designed for courses or self study this book includes numerous exercises and examples that require minimal computer science background making it accessible to novices Experienced practitioners and researchers will appreciate the detailed examples in a wide range of application areas including hardware design image processing access control query optimization and program analysis The last section of the book points out directions for future studies      The Publishers' Trade List Annual, 1995      *Full Abstraction and Semantic Equivalence* Ketan Mulmuley, 1987 Full Abstraction and Semantic Equivalence demonstrates an original theory that uses the same inclusive predicates to show semantic equivalence and to construct fully abstract extensional submodels Previous general techniques for proving semantic equivalence through the construction of inclusive predicates have foundered due to their complexity and the lack of any counter examples In this book Mulmuley has been able to construct a counterexample through diagonalization moreover he has discovered a technique to prove semantic equivalences that has the advantage of being mechanizable This system called Inclusive Predicate Logic IPL can almost automatically prove the existence of most of the inclusive predicates which arise in practice Mulmuley also demonstrates that one can construct a fully abstract algebraic model of typed lambda calculus which is a submodel of the classical model if the classical model is based on complete lattices Beyond this the book shows that theory can extend to the case of a language that has reflexive recursively defined types as do most of the real programming languages Contents Introduction to Domain Theory The Problem of Inclusive Predicate Existence Fully Abstract Submodels of Typed Lambda Calculi Fully Abstract Submodels in the Presence of Reflexive Types A

Mechanizable Theory for Existence Proofs IPL Implementation Conclusion Ketan Mulmuley is a Miller Fellow in the Department of Electrical Engineering and Computer Science at the University of California Berkeley Full Abstraction and Semantic Equivalence is a winner of the 1986 ACM Doctoral Dissertation Award [Computerworld](#) ,1984-02-20 For more than 40 years Computerworld has been the leading source of technology news and information for IT influencers worldwide Computerworld s award winning Web site Computerworld.com twice monthly publication focused conference series and custom research form the hub of the world s largest global IT media network **Computational Limitations of**

**Small-depth Circuits** Johan Håstad,1987 Proving lower bounds on the amount of resources needed to compute specific functions is one of the most active branches of theoretical computer science Significant progress has been made recently in proving lower bounds in two restricted models of Boolean circuits One is the model of small depth circuits and in this book Johan Torkel Hastad has developed very powerful techniques for proving exponential lower bounds on the size of small depth circuits computing functions The techniques described in Computational Limitations for Small Depth Circuits can be used to demonstrate almost optimal lower bounds on the size of small depth circuits computing several different functions such as parity and majority The main tool used in the proof of the lower bounds is a lemma stating that any AND of small fanout OR gates can be converted into an OR of small fanout AND gates with high probability when random values are substituted for the variables Hastad also applies this tool to relativized complexity and discusses in great detail the computation of parity and majority in small depth circuits Contents Introduction Small Depth Circuits Outline of Lower Bound Proofs Main Lemma Lower Bounds for Small Depth Circuits Functions Requiring Depth  $k$  to Have Small Circuits Applications to Relativized Complexity How Well Can We Compute Parity in Small Depth Is Majority Harder than Parity Conclusions John Hastad is a postdoctoral fellow in the Department of Mathematics at MIT Computational Limitations of Small Depth Circuits is a winner of the 1986 ACM Doctoral Dissertation Award **IEICE Transactions on Information and Systems** ,1992 [The Design and Analysis of Efficient Learning Algorithms](#) Robert E. Schapire,1992 This monograph describes results derived from the mathematically oriented framework of computational learning theory [Computing Newsletter for Schools of Business](#) ,1984

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